

## System Stability

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## System Instability: Example



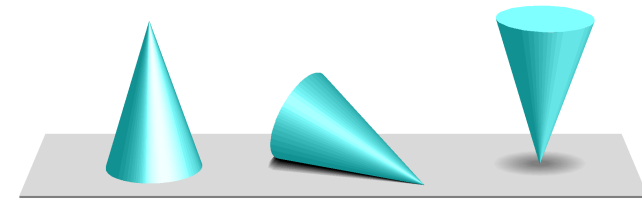
e133.eps

Tacoma Narrows bridge at catastrophic failure



## System Stability

A Stable system is a dynamic system with a bounded response to a bounded input.

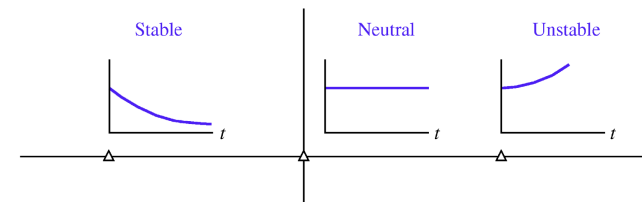


(a) Stable

(b) Neutral

(c) Unstable

e131.eps



Stable

Neutral

Unstable



## Routh-Hurwitz Criterion for Stability

The method involves two steps:

- 1 Generate a data table called a Routh table.
- 2 Interpret the Routh table to tell how many system-poles are in the left half-plane, the right half-plane, and on the  $j\omega$ -axis.

The Routh-Hurwitz Criterion declares that:  
the number of roots of the polynomial that are on the right half-plane is equal to the number of sign changes of the first column of the Routh table.



## Generation of a Basic Routh Table

$$R(s) \longrightarrow \frac{N(s)}{a_4 s^4 + a_3 s^3 + a_2 s^2 + a_1 s + a_0} \longrightarrow C(s)$$

$s^4$	$a_4$	$a_2$	$a_0$
$s^3$	$a_3$	$a_1$	0
$s^2$			
$s^1$			
$s^0$			

e134. eps



Initial layout for Routh table

## Stability Analysis: R-W Criterion

$$\text{Example: } R(s) \longrightarrow \frac{1000}{s^3 + 10s^2 + 31s + 1030} \longrightarrow C(s)$$

$s^3$	1	31	0
$s^2$	<del>10</del> 1	<del>1030</del> 103	0
$s^1$	$\frac{-\begin{vmatrix} 1 & 31 \\ 1 & 103 \end{vmatrix}}{1} = -72$	$\frac{-\begin{vmatrix} 1 & 0 \\ 1 & 0 \end{vmatrix}}{1} = 0$	$\frac{-\begin{vmatrix} 1 & 0 \\ 1 & 0 \end{vmatrix}}{1} = 0$
$s^0$	$\frac{-\begin{vmatrix} 1 & 103 \\ -72 & 0 \end{vmatrix}}{-72} = 103$	$\frac{-\begin{vmatrix} 1 & 0 \\ -72 & 0 \end{vmatrix}}{-72} = 0$	$\frac{-\begin{vmatrix} 1 & 0 \\ -72 & 0 \end{vmatrix}}{-72} = 0$

e136. eps

Two sign changes in the first column, system is unstable since two poles exists in the right half-plane.



$s^4$	$a_4$	$a_2$	$a_0$
$s^3$	$a_3$	$a_1$	0
$s^2$	$\frac{-\begin{vmatrix} a_4 & a_2 \\ a_3 & a_1 \end{vmatrix}}{a_3} = b_1$	$\frac{-\begin{vmatrix} a_4 & a_0 \\ a_3 & 0 \end{vmatrix}}{a_3} = b_2$	$\frac{-\begin{vmatrix} a_4 & 0 \\ a_3 & 0 \end{vmatrix}}{a_3} = 0$
$s^1$	$\frac{-\begin{vmatrix} a_3 & a_1 \\ b_1 & b_2 \end{vmatrix}}{b_1} = c_1$	$\frac{-\begin{vmatrix} a_3 & 0 \\ b_1 & 0 \end{vmatrix}}{b_1} = 0$	$\frac{-\begin{vmatrix} a_3 & 0 \\ b_1 & 0 \end{vmatrix}}{b_1} = 0$
$s^0$	$\frac{-\begin{vmatrix} b_1 & b_2 \\ c_1 & 0 \end{vmatrix}}{c_1} = d_1$	$\frac{-\begin{vmatrix} b_1 & 0 \\ c_1 & 0 \end{vmatrix}}{c_1} = 0$	$\frac{-\begin{vmatrix} b_1 & 0 \\ c_1 & 0 \end{vmatrix}}{c_1} = 0$

e135. eps

Completed Routh table



## Special Cases of R-W Criterion

- 1 Table have a zero only in the first column of a row. In such case, an epsilon,  $\epsilon$ , is assigned to replace the zero and the value of  $\epsilon$  is then allowed to approach zero from either the positive or negative side after which the signs of the entries of the first column can be determined.
- 2 Table have an entire row that consists of zeros. In such case, we return to the row immediately above the row of zeros and form an auxiliary polynomial, using the entries in that row as coefficients. The polynomial is then differentiated with respect to  $s$  to obtain the coefficients to replace the rows of zeros.



## Example of a R-W Criterion: Case 1

$$R(s) \rightarrow \frac{10}{s^5 + 2s^4 + 3s^3 + 6s^2 + 5s + 3} \rightarrow C(s)$$

$s^5$	1	3	5
$s^4$	2	6	3
$s^3$	$\cancel{0} \epsilon$	$\frac{7}{2}$	0
$s^2$	$\frac{6\epsilon - 7}{\epsilon}$	3	0
$s^1$	$\frac{42\epsilon - 49 - 6\epsilon^2}{12\epsilon - 14}$	0	0
$s^0$	3	0	0

e137.eps



Label      First Column       $\epsilon = +$        $\epsilon = -$

$s^5$	1	+	+
$s^4$	2	+	+
$s^3$	$\cancel{0} \epsilon$	+	-
$s^2$	$\frac{6\epsilon - 7}{\epsilon}$	-	+
$s^1$	$\frac{42\epsilon - 49 - 6\epsilon^2}{12\epsilon - 14}$	+	+
$s^0$	3	+	+

e138.eps

The system is unstable, with two poles in the right half-plane



## Example of a R-W Criterion: Case 2

$$R(s) \rightarrow \frac{10}{s^5 + 7s^4 + 6s^3 + 42s^2 + 8s + 56} \rightarrow C(s)$$

$s^5$	1	6	8
$s^4$	$\cancel{7} 1$	$\cancel{42} 6$	$\cancel{56} 8$
$s^3$	$\cancel{0} \cancel{7} 1$	$\cancel{0} \cancel{42} 3$	$\cancel{0} \cancel{56} 0$
$s^2$	3	8	0
$s^1$	$\frac{1}{3}$	0	0
$s^0$	8	0	0

e139.eps



No sign change, stable system

## Case 2: Procedure Steps

- Start by forming Routh table.
- At 2<sup>nd</sup> row, multiply through 1/7 for convenience.
- At 3<sup>rd</sup> row, entire row consists of zeros; then
  - return to the row immediately above the row consisting zeros,
  - form an auxiliary polynomial, using the entries in that row,

$$P(s) = s^4 + 6s^2 + 8 \implies \frac{dP(s)}{ds} = 4s^3 + 12s + 0$$

- the coefficients [4,12,0] are then used to replace the zeros,
  - for convenience, the 3<sup>rd</sup> row is multiplied by 1/4
- Remain of the table is formed in standard manner.

